

1 **Word production: Monitoring, control, and repair**

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29 **Abstract**

30 Research on word production is concerned with the process of turning a thought into motor
31 movements that produce a word. This has traditionally been studied using two approaches, the
32 psycholinguistic approach and the motor speech approach, which focus on different parts of the
33 word production process. In this paper, I will show how highlighting the strengths of these two
34 approaches, as well as merging them with broader frameworks and theories of action and
35 cognition, can take language production research in novel directions. In doing so, I will discuss
36 processes that complement language production, such as how speakers assess whether production
37 is going smoothly (monitoring), adjust to its difficulties (control), and fix errors (repair). Each
38 proposal combines what we know about language production with insights from other areas of
39 cognition. Through these proposals, I will demonstrate the utility and necessity of a closer
40 integration of broader cognitive frameworks into models of word production, as an important
41 general direction for future research.

42

43 **Keywords**

44 Language production, monitoring, control, error repair, decision making, learning

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Word production, monitoring, control, and repair

Introduction

The study of language production is concerned with how people turn their thoughts into speech that is executed through motor movements. Historically, word production has been studied using two approaches: the psycholinguistic approach and the motor speech approach¹⁻³. Generally speaking, the focus of psycholinguistic models is mapping meaning to sound: How do speakers retrieve an arbitrary sound pattern (e.g., /kæt/) to refer to the furry pet? Motor speech models, on the other hand, focus on mapping sound patterns (e.g., /kæt/) to articulatory motor movements^{3,4}. This difference in focus has caused the two approaches to remain largely separate. Moreover, with the exception of motor control research, which has heavily influenced motor speech models, neither approach has, traditionally, made close contact with more general theories of action and cognition.

Each approach has its strengths. The main strength of the psycholinguistic approach is its broader view of language production as a process beyond a mere motor act. The emphasis of psycholinguistic models on semantic knowledge (i.e., concepts) as the starting point of language production, naturally pushes these models to address key issues such as consequences of semantic similarity (i.e., overlap in meaning) and mechanisms that select one word among related words (how do I say *cat*, and not *dog*, when talking about the furry pet?). These issues, in turn, provide a natural bridge to theories of cognitive control, which are concerned with the selection of a response among competing alternatives, and theories of decision-making, which address the factors that affect implicit or explicit selection. Motor speech models, on the other hand, have two key

72 advantages over the traditional psycholinguistic models of adult language production; they view
73 the act of production as closely integrated with (a) monitoring and (b) learning. This close
74 integration of production, monitoring, and learning naturally leads to viewing the language
75 production system as a goal-oriented, self-organizing system, which adjusts itself to different
76 situations and task goals, similar to many other cognitive systems⁵⁻⁷. By this, I do not mean to
77 imply that learning has never been implemented in psycholinguistic models. There are plenty of
78 models that use learning to explain specific phenomena⁸⁻¹¹. However, as will be discussed in the
79 next section, learning and monitoring are not integral parts of the main psycholinguistic models of
80 word production.

81 My goal in the current paper is not to give a comprehensive overview of the models of word
82 production, which exists elsewhere¹²⁻¹⁴, but rather to highlight what can be gained by considering
83 both the psycholinguistic and motor speech approaches and linking them with more general
84 theories of action and cognition. I will do so by focusing on mechanisms of monitoring, control,
85 and repair in production. Monitoring assesses whether production is on track to meet the
86 production goals (e.g., communicating a message). This includes catching errors that may hinder
87 communication. Control defines operations that help production proceed smoothly toward its
88 goals. Repair refers to processes that change an utterance (usually an error) to a new utterance.
89 The discussion of these mechanisms will, in turn, bring out the critical role of learning and decision
90 making in the production process. Throughout the paper, I will use the word “learning” in its
91 computational sense of changing the strength of connections between representations in the
92 production system¹⁵. In this sense, learning is contrasted with changes to the activation of
93 representations without affecting the system’s connections. Note that this definition encompasses
94 explicit and implicit learning, and has the feature of being more resilient against the passage of

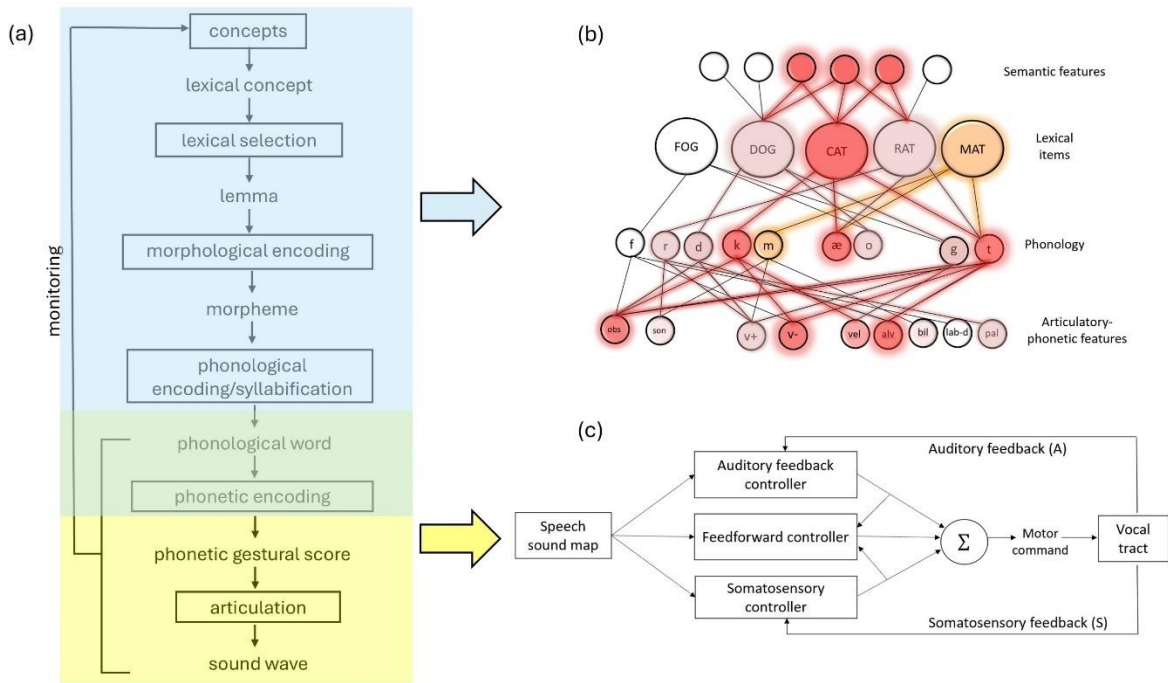
95 time and interference from unrelated representations than activation-based dynamics^{16,17}. I will
96 show that the resulting view offers new perspectives on current hotly debated issues, including the
97 mechanisms underlying word selection and domain-generalty/specificity of control processes that
98 regulate language production.

99 **Computational models of word production**

100 Figure 1a is an overview of the representations involved in the entire production process³.
101 Production starts from concepts and selects the appropriate word (lemma) to express that concept.
102 If the word needs to be inflected (e.g., help → helped), it is morphologically encoded and then sent
103 for syllabification and phonological encoding, where its abstract metric and sound structure is put
104 together. Next, it goes through phonetic encoding which prepares it for articulation. Figures 1b and
105 1c show the rough scope of psycholinguist and motor speech models. Most psycholinguistic
106 models start with concepts but go no further than phonetic encoding. This is not to say that all
107 psycholinguistic models have all these layers; rather, to emphasize that they are rarely concerned
108 with articulatory processes. In contrast, motor speech models usually start with the phonological
109 form or its equivalent in perceptual space and cover the later stages of production. To lay out the
110 foundation for discussing monitoring, control, and repair processes that are the focus of this paper,
111 I will briefly review the main models from the psycholinguistic and motor speech traditions, as
112 well as one model that has attempted to merge the two.

113 Within the psycholinguistic tradition, mapping meaning to sound entails at least two distinct
114 stages¹ (Fig. 1b): mapping semantic knowledge (represented as semantic features) to lexical items
115 (i.e., lexical retrieval) and mapping lexical items to phonology (i.e., phonological encoding). The
116 first step can be influenced by syntactic demands^{1,3}. The second stage can continue on to phonetic
117 encoding but this is skipped in many psycholinguistic models¹⁸⁻²⁰. Two main computational

118 models in the psycholinguistic tradition are Levelt et al. (1999)³ and Dell (1986)¹ and their
119 subsequent versions (see^{12,14} for reviews). While the details and scopes of the two models and their
120 variants differ, they mostly agree on the core representations and the main stages of processing.
121 Importantly, both models emphasize the co-activation of related representations within each layer
122 of the production system (e.g., lexical item *dog* for the target *cat*; Fig. 1a). Modeling such
123 coactivation and its consequences has been one of the major strengths of the psycholinguistic
124 tradition and has fostered several theories including competitive/non-competitive selections and
125 domain-generality/specificity of cognitive control, which I will unpack in the following
126 sections^{8,21–25}. In addition, these models have been quite successful in explaining language
127 impairment after brain damage or aphasia^{19,20,26,27}, capturing the development of word production
128 abilities in children^{28,29}, and mapping language production processes onto brain regions^{30–33}.
129 Finally, psycholinguistic models can accommodate different modalities of language production,
130 including written and typed production^{34,35}. It is worth noting that despite their similarities, the two
131 main psycholinguistic models differ in one key respect, namely, their assumption regarding
132 modularity (see Box 1).



135 *Figure 1. Models of word production. (a) The general architecture of language production from*
 136 *meaning to sound (adopted from³). (b) The two-step interactive model¹. Schematic of spreading*
 137 *activation for a trial with “cat” as the target. Spreading activation to “cat” and competing*
 138 *representations are shown in darker and lighter shades of red, respectively. Phonologically related*
 139 *word “mat” is activated through feedback, and activates its own unique segments through*
 140 *feedforward connections (dynamic shown in orange). For illustrative purposes, only some*
 141 *phonetic features and partial feedback are shown. (c) A simplified version of DIVA (adapted from⁴).*
 142 *See text for model descriptions.*

Box 1. Modularity or interactivity within the language production system

Modularity¹⁷⁰ refers to the encapsulation of information within each stage of processing. Psycholinguistic models agree on the multi-stage nature of word processing (Fig. 1a), but they differ on the issue of modularity. This debate concerns two phenomena, cascading and interactivity. In a system with cascading of activation, information from a higher layer leaks into lower layers, before the higher-level processing has been completed. In an interactive system, information that has cascaded to lower layers also feeds back to higher levels and influences processing in those layers. Levelt et al.'s (1999) model³ does not allow cascading or interactivity and, consequently, is an example of a modular model, whereas Dell's (1986) model¹ is a prime example of an interactive model. Figure 1a shows principles of cascading and interactivity when the speaker successfully produces the target "cat". Cascading is reflected in the activation of some of the phonology of the competing lexical items that were not ultimately selected (e.g., /d/ for dog)¹⁷¹. This is not expected in a model without cascading, because phonological activation only starts after a lexical item has been selected. Interactivity is shown in the activation of the lexical item "mat" through feedback from its segments /æ/ and /t/^{96,172,173}.

Several behavioral and neural findings now support non-modular models. For example, when participants named a picture as a couch, they were nevertheless faster at reading the following probe "soda", which was related to the alternative label sofa, compared to an unrelated word¹⁷¹. This finding shows cascading because to prime "soda", participants must have activated the alternative label (sofa) down to at least its phonological representations, even though they obviously did not select it at the lexical level. Similarly, cascading between phonemes and articulatory-phonetic features was supported by the finding that segmental errors (e.g., /k/ → /g/) had a voice onset time somewhere between target and error phonemes, showing that the articulated

168 product was a blend of the two phonemes¹⁷⁴. Interactivity has also found support in a number of
169 behavioral findings, including the mixed error effect¹, the lexical bias effect¹⁷⁵ cf.,¹⁷⁶, and the
170 repeated phoneme effect^{1,34}. Neural data tell a similar story. Manipulating semantic similarity has
171 effects on later processes, up to articulation, and manipulating segmental similarity affects earlier
172 processes through feedback⁶⁰.

173 Although the evidence cited above supports non-modular systems, they should not be taken as
174 support against distinct processing stages¹⁷⁷ for two reasons. First, due to the mostly arbitrary
175 mapping between semantic features and sounds of words, a single-stage mapping achieved by
176 direct connections from individual semantic features to individual sounds is not possible. Also,
177 even the behavioral and neural evidence that supports cascading and feedback points to a system
178 that retains some modularity^{60,164}. The modularity debate is not just of abstract theoretical interest⁵;
179 it has important consequences for the application of theoretical models to new data. For example,
180 interpreting EEG components or fMRI activity as reflecting a specific process based on a timeline
181 derived from a serial (modular) model^{31,178} can be problematic, because such an approach neglects
182 the fact that the current component/neural region is influenced by processing in layers before and
183 after it (see¹⁷⁹ for a critical review of this approach and its problems).

184
185 The main model from the motor speech tradition is Guenther's directions into velocities of
186 articulators (DIVA) and its later version, gradient order DIVA or GODIVA^{2,36,37}. The model is
187 essentially a forward model of motor control (Fig. 1c). Forward models predict the consequences
188 of motor commands through internal simulations of movements³⁸⁻⁴⁰. The model starts by
189 activating the sound of a word in the speech sound map. A speech motor command is sent to the
190 articulators to produce the word. Simultaneously, the perceptual consequences of this motor

191 command are anticipated in the form of auditory and somatosensory predictions. Once the word
192 has been spoken, the actual perceptual auditory and somatosensory consequences are compared to
193 the anticipated ones. If there are any discrepancies, an error signal is generated, which is used by
194 an inverse model to adjust future motor movements. DIVA and its variants explain a wide range
195 of findings in the acoustic-articulatory part of the language production system. These include
196 learning to produce novel sounds and adjusting speech based on altered auditory or somatosensory
197 feedback, as well as disorders that affect sublexical representations, such as stuttering and apraxia
198 of speech⁴¹⁻⁴⁴. Moreover, these models have allowed for a detailed neural mapping of speech
199 planning and execution processes to both cortical and subcortical regions^{4,45,46}.

200 To date, no computational model has preserved the sophistication of GODIVA's account of
201 articulation in a model that also addresses psycholinguistic issues, such as lexical access from
202 meaning, but some models have incorporated elements from both. An example is Hickok's (2012)
203 hierarchical state feedback control model⁴⁷. The model is similar to DIVA in assuming that
204 perception controls production but changes the starting point from the speech sound map to the
205 psycholinguistic concept of lemma³. The lemma hierarchically activates syllables and phonemes,
206 each of which have their own perceptual control loops (auditory and proprioceptive, respectively).
207 However, unlike DIVA, the hierarchical state feedback control model does not depend on overt
208 consequences of action. Rather, lemma activation is hypothesized to activate both motor and
209 perceptual representations, with the former suppressing the latter. A correct production of the target
210 extinguishes the activation of the target's perceptual representation, but an error fails to do so,
211 leading to the generation of an error signal. In proposing an internal check process independent of
212 overt perceptual feedback, the model appeals to psycholinguistic notions such as "inner speech"⁴⁸,
213 while maintaining a core assumption of motor speech theory, i.e., the reliance of the speech

214 production system on the perceptual system. However, the model does not implement the first
215 stage of processing, i.e., semantic-to-lexical mapping.

216 As shown in this brief overview, psycholinguistic models pay much attention to the coactivation
217 of representations, while motor speech models highlight the interaction between perception and
218 production systems. In the next section, I will review how this differential emphasis can be
219 leveraged for monitoring and control of the language production system.

220 **Monitoring**

221 As noted earlier, one of the strengths of motor speech models is that monitoring and control are
222 integral to the production process. As seen in Fig. 1c, every act of production is accompanied by
223 parallel activation of sensory representations that act as a “check” on production. Psycholinguistic
224 models, on the other hand, do not pose an integral monitoring mechanism. Instead, for example,
225 in Levelt et al.’s (1999) model, the language comprehension system is in charge of monitoring
226 production. This account, called the “perceptual loop”⁴⁹, is elegant in its assumption that the same
227 system used for monitoring the speech of others, is also used for monitoring one’s own speech⁵⁰.
228 The proposal has an outer loop and an inner loop. The outer loop is simply speech comprehension,
229 the contribution of which to monitoring can hardly be denied; we hear ourselves all the time and
230 such prominent input can hardly be ignored. The nature of the inner loop has been long debated
231 and criticized^{51–53}. More recently, Roelofs (2020)⁵⁴ has redefined the perceptual loop as
232 connections between representations in the production system and their corresponding
233 representations in the perceptual system. This redefinition makes the perceptual loop account more
234 similar to that of speech motor models.

235 Monitoring production through perception works well when production and perceptual
236 representations are distinct. This is certainly true for the lower post-lexical aspects of production
237 (articulatory-phonetic representations) and perception (acoustic representations), and possibly also
238 for phonology^{20,55}. At higher layers of the production system, i.e., lemmas and higher (Fig. 1a),
239 there is less motivation for, and evidence of, distinct production and perceptual representations.
240 For example, it is unclear why there would be two sets of lemmas, one for perception and one for
241 production, and even less clear why there would be two sets of semantic or syntactic features^{56,57}.
242 Yet, problems can also arise in those layers. One possibility is that higher-level representations are
243 only monitored through the implementation of their sensory-motor representations. This would
244 imply that errors arising during semantic-to-lexical mapping (e.g., *cat* → *dog*) and those arising
245 during lexical-to-phonological mapping (e.g., *cat* → *dat*) are both detected based on the same
246 sensory-motor representations. However empirical evidence suggests a double dissociation in the
247 detection of semantic and phonological/phonetic errors, as well as distinct neural correlates for
248 monitoring these two error types^{52,58,59}. Also, EEG studies in both linguistic and non-linguistic
249 tasks have revealed an early negativity (too early to be compatible with sensory-motor
250 comparisons) in trials with a higher, compared to lower, error likelihood^{60,61}. It thus seems that
251 speakers are equipped with a mechanism to detect the likelihood of an error early on, perhaps
252 before it has even occurred. One way to model the early detection of errors is the conflict
253 monitoring account.

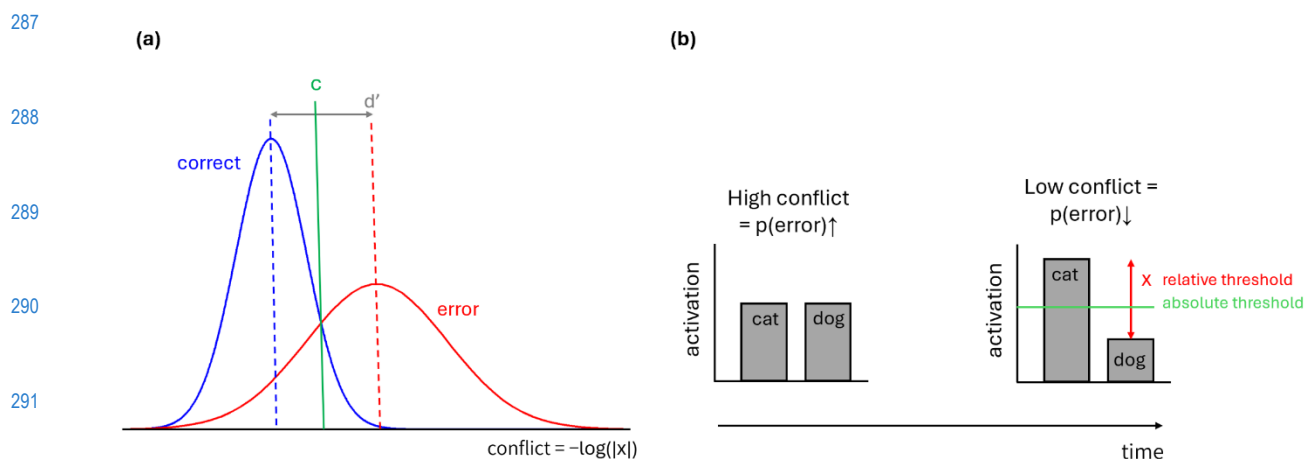
254 The conflict monitoring account^{52,61,62} proposes that production errors are detected by indexing the
255 level of conflict in the activation of competing representations. When one item is much more
256 activated than others, conflict is low, and so is the probability of an error (Fig. 2). Conversely,
257 when two or more items have comparable activation levels, conflict is high, and errors are more

258 likely. Importantly, conflict monitoring can happen at any stage of production, and is not bound to
259 sensory-motor representations. Also, it can be easily implemented in psycholinguistic activation
260 models, which emphasize the coactivation of competing alternatives.

261 But what level of conflict should be considered “high”? Answering this question requires using a
262 decision-making framework. Figure 2a shows the application of signal detection theory’s (SDT)⁶³
263 framework to the distribution of conflict for correct and error trials. SDT has been one of the most
264 influential theories in psychology. In its original form (SDT-I), it contains distributions of signal
265 and noise and models decisions attributing a stimulus to one of these two distributions. Imagine
266 being asked to detect a tone amid noise. Within SDT, your choice is affected by two parameters
267 (Fig. 2a). Discriminability or d' determines how separable the two distributions are. The higher the
268 d' , the more accurate the choice. Criterion or c indicates a threshold (a point somewhere on the
269 distributions) your system defines to label a stimulus as signal or noise. This results in four types
270 of responses. If a stimulus belongs to the signal distribution and is above the criterion, it is correctly
271 labeled as a signal (Hit). If the same is below the criterion, it is erroneously labeled as noise (Miss).
272 Similarly, if a stimulus belongs to the noise distribution and is below the criterion, it is correctly
273 labeled as noise (Correct Rejection). If the same happens to be above the criterion, it is mistakenly
274 labeled as signal (False Alarm).

275 SDT-II⁶⁴ applies the same framework to metacognitive judgments. Now judgments are not on
276 external stimuli but on cognitive choices themselves. In language production, instead of
277 distributions of signal and noise, we have distributions of conflict for error and correct trials. D'
278 depends on the state of the production system and the nature of the task. Healthy mature production
279 systems have a high d' . Damaged (e.g., post-stroke), immature (e.g., child), or lightly trained (e.g.,
280 L2 speakers) systems have lower d' s^{52,65,66}. This usually means that correct trials in these systems

281 are also associated with higher amounts of conflict, making the two distributions less
 282 distinguishable. Criterion c depends on task goals⁶. If accuracy matters, c is set conservatively
 283 (low misses at the cost of higher false alarms). If speed and fluency matter more, c is set liberally
 284 (low false alarms at the cost of higher misses). False alarms, although uncommon, can be observed
 285 in individuals with aphasia as changing a correct response into an error^{52,67}, and in neurotypical
 286 speakers, as disfluencies⁶⁸.



293 *Figure 2. The relationship between conflict and response selection. (a) Hypothetical distributions*
 294 *of conflict for correct and error trials, within the signal detection framework. D' reflects how*
 295 *cleanly separable the two distributions are. Criterion c can be put anywhere on the axis of*
 296 *conflict. Shifting c to the left makes behavior more conservative (fewer misses, more false alarms),*
 297 *whereas shifting c to the right makes behavior more liberal (fewer false alarms, more misses). (b)*
 298 *Change in conflict over time. A high-conflict trial can turn into a low-conflict trial over time*
 299 *(through spreading activation in neural networks or evidence accumulation in decision models).*
 300 *Conflict is inversely related to the difference between the activation of two (or more) items (x in*
 301 *the right-most figure). A competitive selection mechanism critically depends on reaching a certain*

302 *value of x (a relative threshold). Non-competitive selection only needs an absolute threshold,*
303 *irrespective of x (green).*

304 For selection, the decision rule is: *if conflict $< c$, then select; otherwise, wait* (until conflict gets
305 smaller with further spread of activation; Fig. 2b). For monitoring, the decision rule is: *if conflict*
306 *$< c$, then pass as correct; otherwise, detect as an error.* The selection and monitoring rules only
307 differ in *when* they apply, with selection tending to occur earlier. In an ideal world, conflict
308 monitoring would always operate before selection, preventing all errors. However, this could lead
309 to silences and pauses that speakers may wish to avoid, leading them to sometimes commit to
310 responding before checks are complete. This would manifest as overt errors needing detection and
311 repair, although the rate of overt errors remains low in healthy mature systems⁶⁹.

312 To summarize, applying SDT rules over distributions of conflict allows us to understand selection,
313 monitoring, and error detection within the same framework. In a similar way, SDT can be used to
314 determine the parameters of error detection within other frameworks, although the nature of the
315 distributions depends on the information that those theories consider central to monitoring. Two
316 issues merit further discussion: the first issue is whether selecting the word *cat* depend on how
317 activated *cat* is per se, or how much more activated *cat* is compared to *dog* (Fig. 2b)? This question
318 is at the heart of the mechanisms of lexical selection. The second issue concerns better
319 computational approaches to understanding the first issue. Boxes 2 and 3 address these two points,
320 respectively.

321 [Boxes 2 and 3 about here]

322 ***Towards a more comprehensive model of monitoring***

323 There is an ongoing debate about which monitoring mechanism is the right one^{53,54}. My own view
324 is that language production is monitored through a combination of mechanisms. The original
325 perceptual loop model assumes a conscious deliberate monitoring through the comprehension
326 system⁴⁹. Despite attempts at dialing back the role of conscious awareness in the more recent
327 versions of the perceptual loop⁵⁴, I think the emphasis on conscious and deliberate processing is
328 actually a great asset of the original theory. It affords monitoring a place for taking into account
329 the speaker's broader knowledge of the world. In fact, the role of deliberate monitoring extends to
330 monitoring the audience for signs of incomprehension and actively using world knowledge and
331 common ground to facilitate communication.

332 Complementing these conscious processes are implicit mechanisms that have the advantage of
333 being fast and effortless. Forward models are excellent candidates for this purpose at the sublexical
334 level, i.e., for the detection of phonological/phonetic errors or adjusting acoustic properties of
335 speech⁷⁰⁻⁷⁴. Classic forward models like DIVA, however, monitor the overt consequences of
336 behavior, precluding them from detection of *potential* errors. Moreover, speakers can detect errors
337 in their silent, unarticulated inner speech, which has no overt perceptual consequences⁴⁸. In these
338 cases, detection mechanisms such as those proposed in the hierarchical state feedback control
339 model or conflict monitoring provide a better explanation. Finally, models that hinge on sensory-
340 motor interactions are not the best candidates for monitoring more abstract representations, while
341 empirical evidence shows that such representations can indeed be monitored. Conflict monitoring
342 proposes a solution for these cases. Note that both forward models and conflict monitoring follow
343 the same fundamental principle of using information to predict the outcome. As such, rather than
344 thought of as opposing theories, they may be better conceived of as complementing theories. Box
345 4 discusses these theories within the broader umbrella of the reinforcement learning theory⁷⁵.

Box 2. Is lexical selection competitive or not?

When we intend to say *cat*, does it matter how activated *dog* is? Much research has shown that increasing semantic similarity, especially taxonomic similarity (cat/dog), between a target and its context interferes with production (see ^{179,180}for reviews). Many such claims hinge on results from the picture-word interference (PWI) paradigm¹⁸¹, where participants must name a picture ignoring a distractor word that usually appears in written form on top of the picture. PWI has been criticized^{23,182} for its many complexities such as multimodal processing that inevitably involves other systems (e.g., reading) and the need for suppressing a prepotent response, which is not the norm in speaking. However, semantic interference has also been robustly demonstrated in other paradigms, such as blocked cyclic naming¹⁸³ where participants repeatedly name a small set of items, and its more ecologically valid variant, continuous naming, where people simply name a sequence of pictures^{17,177}. For decades, such interference was taken as evidence for “competitive lexical selection”^{3,21,24,184}. The idea is that lexical selection can only proceed after a relative threshold, i.e., a minimum difference between the activation of target and competitor(s), has been reached (x in Fig. 2b). Opposing this idea, some researchers showed that production can be facilitated in semantically similar contexts, especially for thematic relations (bone/dog). This finding was taken as evidence for “non-competitive lexical selection”^{23,185,186}. The idea here is that an item can be selected as soon as it passes an absolute threshold, without being affected by the activation of competing representations (see Fig. 2b).

Three points are noteworthy regarding this debate. First, while some computational models explicitly depend on competitive selection to explain interference and facilitation (e.g.,²⁴ and variations), others do not^{8,9,144}. Importantly, the latter type relies on incremental learning mechanisms to explain these effects^{8,9,144,172,187}. One such mechanism is error-based learning⁹.

369 When *cat* is the target of production, its shared semantic features with *dog* also activate the word
370 *dog*. At the end of production, error-based learning mechanisms strengthen the connections
371 between the target (*cat*) and its semantic features while simultaneously weakening the connections
372 between the competitor (*dog*) and the features it shares with the target. This learning mechanism
373 facilitates the retrieval of *cat* when it next becomes the target (i.e., repetition priming¹⁸⁸), but
374 interferes with a subsequent production of *dog*. A similar mechanism can explain interference in
375 segmentally related contexts^{172,187}. Adopting the learning account has two advantages: (a) it
376 explains the longevity of interference induced by contextual similarity^{17,183}. Note that other
377 learning models that do not weaken the competitor's connections can explain long-term priming,
378 but do not explain long-term interference without additional mechanisms¹⁸⁸. (b) When combined
379 with a more accurate representation of semantic relationships, it naturally accommodates the
380 seemingly disparate facilitation and interference effects induced by thematic and taxonomic
381 relations, respectively, which have been previously taken to imply mutually exclusive selection
382 rules. Specifically, combining incremental learning mechanisms with the gradual activation of
383 themes, captures thematic facilitation and taxonomical interference, irrespective of whether the
384 model's selection rule is set to competitive or non-competitive⁸.

385 The second point worth noting is that the models that explain similarity-induced interference via
386 learning do not necessarily deny the existence of mechanisms that impose some degree of
387 competitive selection, such as lateral inhibition. In fact, given the prevalence of inhibitory
388 interneurons and lateral inhibition in cognitive systems^{189,190}, it would be strange to insist that the
389 language production system is devoid of such connections. Acknowledging lateral inhibition
390 naturally implies some competition in the system, which also motivates and constrains the use of
391 measures such as conflict (i.e., conflict is not just measured between any two arbitrary

392 representations, but between those with mutual inhibitory effects). However, the existence of
393 lateral inhibition does not automatically endorse competitive selection accounts. It is theoretically
394 possible to have lateral inhibition and still select a representation before lateral inhibition has
395 driven down the competition below a fixed value of x (Fig. 2b), which brings me to point 3.

396 The third noteworthy point is that the debate assumes a dichotomy: Selection is either competitive
397 or not. My own view is that such a binary view is incompatible with the workings of a highly
398 adaptive goal-oriented system such as language production^{6,7}. I believe that the concept of a
399 relative threshold x is useful, but this threshold can vary to ignore or highlight competition
400 depending on the situation and task goals¹⁹¹. For example, imagine I am talking to a friend about
401 the chance of rain in the afternoon, and the words "likelihood" and "probability" both come to my
402 mind. I would output either one quickly to keep the conversation going, knowing that the slight
403 difference in meaning would not alter my message. This is the equivalent of setting a low value of
404 x for the relative threshold. However, if I am teaching statistics and these two words come to mind,
405 I would pause and deliberate to make sure one is the clear winner for the concept I am about to
406 express. This is the equivalent of setting a high value for x . Importantly, I can change x flexibly as
407 my goals for speed vs. accuracy change. This is the idea of a flexible criterion^{6,7,191}.

408

409 **Box 3. Beyond SDT**

410 While SDT provides a simple and useful framework for understanding the relationship between
411 conflict, selection, and error detection, other kinds of decision models can also be applied to
412 language data and have certain advantages over SDT. An example is evidence accumulation
413 models (EAMs)^{192,193}. I have dedicated a box to them here because (a) they have already been used

414 to model certain aspects of language processing^{167–169}, so it is important to be aware of some of
415 their basic features, and (b) they can be an excellent tool for examining competitive vs. non-
416 competitive selection mechanisms (Box 2).

417 Similar to SDT, they model choice based on evidence, but they also consider time, allowing
418 evidence to accumulate gradually. The parameters of EAMs can be estimated through the
419 quantitative fitting of choice-response time distributions. Similar to d' and c in SDT, EAM's *drift*
420 *rate* and *response threshold* parameters are related to the quality of evidence, and the selection
421 criterion, respectively. Mapped onto the lexical selection process, drift rate is akin to how quickly
422 and strongly lexical items gain activation from semantic features. Response threshold is set by the
423 selection rule. Given the close correspondence between EAM's parameters and dynamics of
424 activation and selection, these models appear to be a good tool for examining the mechanisms of
425 lexical selection. But which model is appropriate model for this purpose?

426 EAMs come in many different flavors. Some, like the linear ballistic accumulator (LBA)¹⁹⁴ and
427 racing diffusion model (RDM)¹⁹⁵, are inherently non-competitive, i.e., evidence for one choice is
428 not evidence against another. In contrast, other variants such as the diffusion decision model
429 (DDM)¹⁹⁶ are inherently competitive, with evidence for one choice always counting as evidence
430 against the other. Fully competitive models like the DDM are often limited to binary choices
431 (although extensions to multiple choices do exist¹⁹⁷), whereas accumulator and racing diffusion
432 models more naturally accommodate multiple choices. At first glance, it appears that none of these
433 models is well-suited for addressing the issues raised in the selection debate (Box 2): being limited
434 to two choices is incompatible with the many linguistic choices faced by speakers, and utilizing
435 models that naturally accommodate more choices means committing, a priori, to non-competitive
436 selection.

437 However, while these models are sometimes used in their simplest form, they can also be used as
438 building blocks for more complex models. For example, although LBA is not inherently
439 competitive, competition can be introduced into the model in several ways. One such way is to set
440 up the accumulators to represent relative information, e.g., the presence of one stimulus over
441 another¹⁹⁸. Another way is to build inhibitory connections between the accumulators¹⁹⁹ (see also
442 leaky competing accumulator²⁰⁰). The resulting models can capture competition effects without
443 being restricted to two choices. Customized modeling of competition as inhibitory weights has an
444 additional advantage: the inhibition parameter (i.e., the value(s) of the inhibitory weights) can vary
445 freely and continuously. This continuity allows the model to go beyond a binary competitive/non-
446 competitive distinction, and capture graded competition effects, something that fully competitive
447 models like the DDM cannot do. Such an approach is well-suited for investigating mechanisms of
448 lexical selection and criterion setting, including the degree of competitiveness, its timeline during
449 the evidence accumulation process²⁰¹, and its possible fluctuations across individuals, conditions,
450 and even trials.

451 Despite this clear promise, challenges remain in applying EAMs to language data. For example,
452 EAMs usually require a large amount of data to generate stable and recoverable parameters.
453 Moreover, assumptions such as a constant rate of evidence accumulation within a trial, often made
454 in the LBA, are probably too simplistic for the complex production process. Luckily, many such
455 issues are also of great interest to decision scientists, and new solutions are being continuously
456 investigated. For example, new Bayesian approaches allow for better fits and model-check routines
457 with sparser data²⁰², and a newer variant of LBA employs a non-stationary process of evidence
458 accumulation²⁰³.

459 In short, EAMs are promising models for studying a range of issues related to selection,
460 monitoring, and control in language production, however, their application to linguistic data can
461 be complicated. This challenge can be overcome by a closer collaboration between language and
462 decision scientists, and will likely benefit both fields.

463

464 ***Box 4. Reinforcement learning, conflict monitoring, and forward models***

465 Are conflict monitoring and forward models in opposition to one another? In my mind, these are
466 not mutually exclusive theories. In fact, both fit quite well within a broader framework of a more
467 general, well-implemented, and biologically plausible theory of human behavior, the
468 reinforcement learning (RL) theory⁷⁵. RL's main claim is that humans learn from the consequences
469 of their behavior; positive outcomes reinforce a behavior, whereas negative outcomes discourage
470 the behavior. This framework is naturally well-suited to monitoring, as the point of performance
471 monitoring is precisely to ensure that desired outcomes are reached. Hierarchical versions of RL
472 can include a sequence of actions to model complex tasks, e.g., cooking a meal. Such models allow
473 the agent to predict the final outcome from earlier stages. A model-free RL simply links actions
474 with rewards. In a model-based RL, some internal representation of an action is used to predict
475 action outcomes. Below, I will discuss how conflict monitoring and forward models of language
476 monitoring fit the framework of model-based hierarchical RL.

477 Many of the just criticisms raised against conflict monitoring take issue with “the brain as a conflict
478 detector”²⁰⁴ (see ⁸¹for a review). A good example of this is the debate between RL and conflict
479 monitoring on the role of the anterior cingulate cortex (ACC)^{61,204}. Both theories can explain the
480 ACC-generated EEG marker of error commission, the error-related negativity (ERN). Conflict

481 monitoring also explains an earlier EEG signature (N2)⁶¹ observed in high-conflict trials,
482 regardless of their outcome, but has been criticized for not explaining a late EEG signature in
483 response to external feedback²⁰⁴. One way to tackle this is to show that a neurobiologically
484 plausible computational model of RL generates a pattern that is well-aligned with the predictions
485 of conflict monitoring, showing that the two are not in opposition²⁰⁵. However, and much more
486 importantly, conflict monitoring, at least as I am using it in this paper, is fundamentally not a theory
487 about neural processing. Nor does it mean to replace memory and learning processes²⁰⁶. It simply
488 proposes computations predictive of performance outcomes that are themselves products of
489 learning, memory, and other cognitive processes (see a similar dissociation between quantum
490 computation and quantum brain²⁰⁷).

491 Insofar as conflict computations are good outcome predictors, the theory is useful. For example,
492 we have shown that conflict is a reliable index of a language system's health and maturity, which
493 in turn predicts the probability of speech errors^{52,65}. Naturally, if a situation is created in which
494 conflict is irrelevant or conversely related to performance outcomes, there is no good reason to
495 expect conflict monitoring to be useful, but the main point is that such situations are not the norm
496 in cognitive systems. Moreover, conflict monitoring is successful precisely because it presupposes
497 a trained internal model (e.g., semantic → lexical item → phonology → articulatory phonetics, in
498 case of language production), shaped systematically and hierarchically such that information in
499 earlier stages is predictive of the final outcome, exactly as presumed by model-based RLs.
500 However, the theory does not specify how such a hierarchy has come to be.

501 Forward models provide mechanistic explanations for how hierarchies of actions are shaped
502 through feedback from their sensory consequences (hence my emphasis on the integral role of
503 “learning” in these models). Once formed, the models predict the consequences of motor

504 commands through internal simulations of movements^{38,39}, as in model-based RL. The idea of
505 internal simulations of performance used as predictions is well-supported in biological
506 sensorimotor control⁴⁰. The key issue in applying these models to language production is
507 implementation. A useful model makes precise and testable predictions. This is the case for
508 DIVA/GODIVA, which I have discussed in some detail in this paper. Other proposals exist for
509 expanding the role of forward modeling to all layers of the production system²⁰⁸, but this model
510 has been justly criticized for its ambiguity and lack of clear testable predictions²⁰⁹. An
511 implementation of such models, if successful, would be a valuable contribution to the language
512 monitoring literature.

513 In short, conflict monitoring and forward models, as computational rather than neural theories,
514 both hinge on predictive processing and outcome evaluation within a task hierarchy, which is the
515 tenet of the hierarchical model-based RL. Opposition only arises when conflict monitoring is taken
516 as a core mechanism operating regardless of performance outcome, in which case, the theory loses
517 its sense and value. Also, note that the neural circuitry underlying reward processing in RL theories
518 includes regions like the medial prefrontal cortex²¹⁰ and cerebellum²¹¹. As such, uncovering the
519 involvement of these regions in language monitoring is not unique support for forward models,
520 but is compatible with any model that works within the RL framework.

521 In summary, I believe that language is monitored through multiple mechanisms, including
522 conscious deliberate processes that adjust communication based on speaker's world knowledge
523 and their goals, as well as implicit and largely subconscious processes that use a variety of
524 information at different stages to predict performance outcome. This multi-process monitoring
525 view^{53,76} finds support in empirical evidence, such as bimodal distribution of latencies related to
526 error detection⁷⁷ and distinct neural signatures for errors detected with full and partial sensory

527 feedback⁷⁸. It is also compatible with computational models of error detection⁷⁹, and is aligned
528 with the well-known redundancies in monitoring other functions. An example is gait and posture⁸⁰.
529 The control of normal gait and posture taps into multiple channels of information, including
530 somatosensory, visual, and vestibular sensations. When deviating from the routine, e.g., walking
531 on rough terrain, additional processes are required for gait adjustment. These include cognitive
532 processes that represent the agent's knowledge of their body and motion in space. Importantly,
533 certain parts of the neural circuitry underlying gait and posture control, such as the cerebellum, are
534 involved in all processes that control gait, similar to what has been argued in Box 4 for language
535 monitoring. Luckily, recent advances in the closer integration of monitoring processes with core
536 production processes means that attempts to merge psycholinguistic and motor speech models will
537 also bring together various monitoring mechanisms and nudge us closer to the implementation of
538 the multi-process monitoring view.

539

540 **Control**

541 Monitoring provides valuable information, but such information is only useful when it can be used
542 to regulate the production system. I refer to this as cognitive control or simply “control”. Generally
543 speaking, cognitive control refers to operations that allow humans to behave flexibly in a goal-
544 directed manner⁸¹. Several taxonomies have been proposed, of which Miyake's division of these
545 functions into prepotent response inhibition, task shifting, and working memory updating is
546 probably the most well-known⁸². But this taxonomy was based on experimental tasks already
547 identified as tapping cognitive control, which leaves many real-life situations undefined. For
548 example, what about the inhibition of highly activated competitors in language production? Do we
549 need cognitive control to suppress “dog” when meaning to say “cat”? Is an agreement error like

550 “The snake next to the brown lions are green.” due to the failure of inhibitory control? Errors
551 resulting from competition of a co-activated representations can be identified at all levels of
552 language production, and there has been a movement in the field to link them to failures of
553 inhibitory control^{67,83–87}. This leaves open the question: is there a single “domain-general”
554 inhibitory control ability underlying all tasks and domains?^{88–92}. Alternatively, control may be
555 specific to domain and even task^{22,93,94}. This is the question I will address in this section.

556 *Is all inhibitory control the same?*

557 Competition between the target and competitors in the language production system can create one
558 of two scenarios: (a) cases where the stimulus-driven (bottom-up) information is sufficient to
559 arrive at the correct response, and (b) cases where such information alone leads to the incorrect
560 response. An example of (a) is naming a picture (e.g., *dog*) after having named a similar picture
561 (e.g., *cat*)^{95–98}. Although the similarity creates interference (Box 2), the information provided by
562 the stimulus, i.e., the current picture, is aligned with the task goal of naming that picture. An
563 example of (b) is Stroop-like tasks, where a prepotent response must be suppressed in favor of a
564 less potent response, for example when for social reasons, one must produce a flattering word to
565 describe a disliked object. Here, the stimulus-driven information would lead the speaker to utter a
566 word that is incompatible with the task goal of being polite. Figure 3a shows an example of these
567 two situations, implemented within an experimental paradigm with only two items per block (e.g.,
568 *cat/dog*)^{60,97}. In one condition, the task goal is to name the current picture, but the similarity
569 between the current and the previous item creates behavioral interference (see Box 2). In another
570 condition, the task goal is to reverse the names of the two pictures (i.e., say *cat* when you see the
571 dog and vice versa), creating a Stroop-like effect. While both situations can trigger the monitor to

572 detect an increased need for control, there are both theoretical and empirical reasons to doubt that
 573 they recruit comparable control mechanisms.

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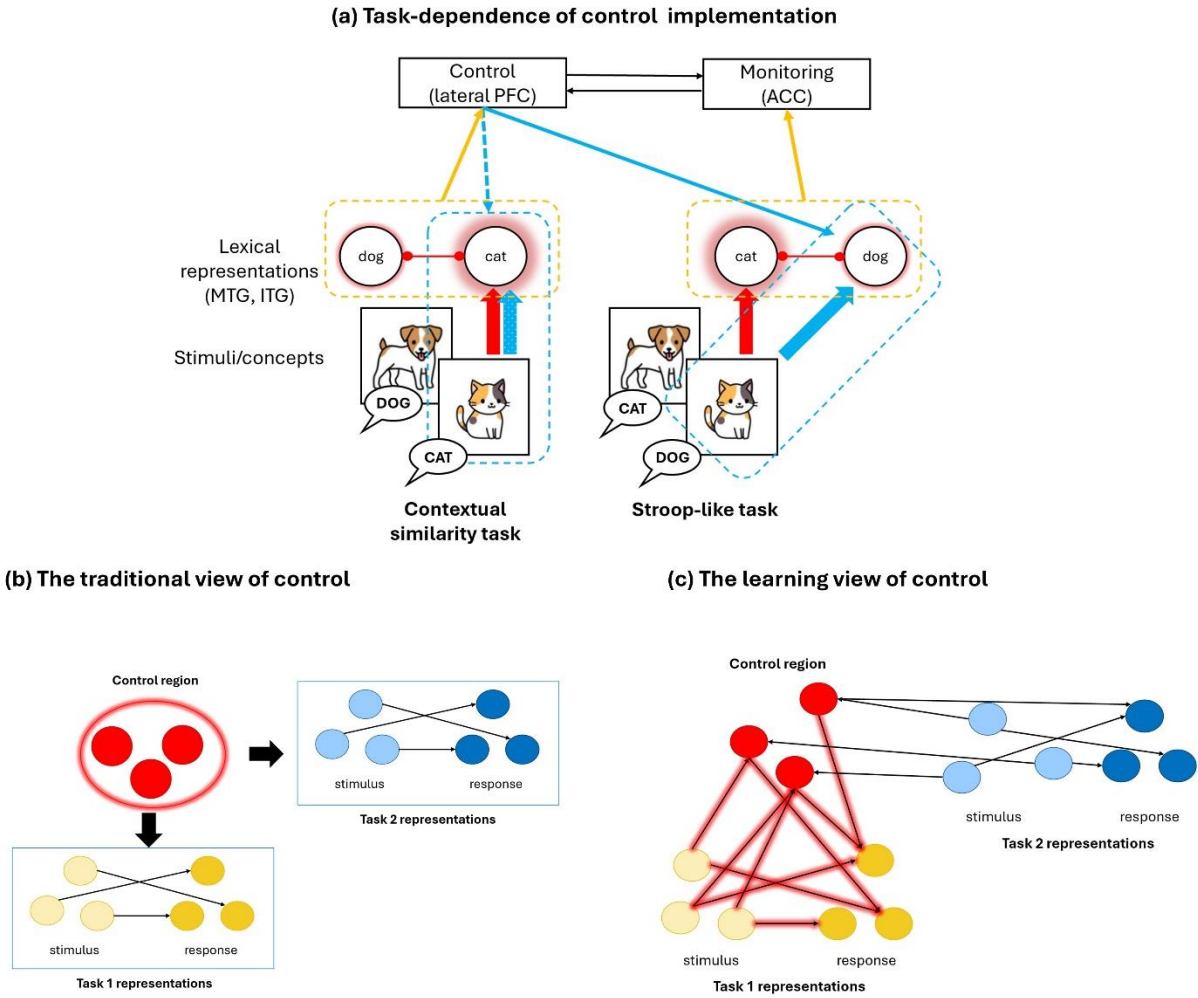
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586 *Figure 3. Control implementation. (a) Task-dependency of control. On the left, the task is to name*
 587 *the current picture. External control (blue arrows) is optional because it will push processing in*
 588 *the same direction as bottom-up information (red arrow). On the right, the task is to use the other*
 589 *label for naming the current picture. Since bottom-up information is insufficient to arrive at the*
 590 *correct response external control is necessary. (b) Traditional view and (c) Learning view of*
 591 *cognitive control (adapted from¹⁴⁵). Both accounts assume domain-generality in neural correlates*

592 *of central control (red circles), but different mechanisms for control implementation, and therefore*
593 *different predictions regarding domain-generality in application. See text for details.*

594 Theoretically, external control is not required to achieve the goal when bottom-up information
595 biases processing towards the correct response. When the goal is to name the current picture “cat”
596 (Fig 3a, left), spreading activation from cat’s semantic features activates the word “cat”. As the
597 word “cat” gains more activation, the local inhibitory link to the word “dog” suppresses the latter
598 (lateral inhibition). If “dog” is very active, this suppression may take some time, but has a high
599 likelihood of ultimately ending in the correct response. Now imagine a Stroop-like situation, where
600 the stimulus is the same, but the speaker’s goal is to say “dog” (Fig 3a, right). The dynamics
601 explained above will not achieve this goal; the speaker will end up saying “cat”, as shown in by
602 the red arrow. In such a case external control is required to bias processing based on the task goal⁹⁹
603 (blue arrow mapping the stimulus to the goal-directed lexical representation). In short, the
604 implementation of external control is essential for producing the correct response in one case, but
605 not the other, pointing to possibly distinct control mechanisms in these two situations.

606 In keeping with this theoretical division, behavioral evidence shows that the magnitude of
607 interference in the contextual similarity task is sensitive to the layer in which competition is
608 induced (semantic vs. phonological), but the magnitude of Stroop-like interference is not^{60,86,97}.
609 This finding points to a more local inhibitory mechanism in the former than the latter case. Neural
610 evidence is also generally aligned with this position. Both situations activate medial PFC, such as
611 the anterior cingulate cortex (ACC), which is known to be involved in monitoring^{100–104}, however,
612 lateral PFC, which is often considered to implement control in collaboration with ACC, is
613 consistently implicated in Stroop-like tasks, but not in tasks that manipulate contextual

614 similarity^{103,105,106}. Further highlighting the differences in these control mechanisms are findings
615 of distinct electrophysiological signature for Stroop-like and similarity-induced interference⁶⁰.

616 In short, task demands and their relation to stimulus-driven information determine whether lateral
617 inhibition between local representations (e.g., middle and inferior temporal gyrus; MTG, ITG for
618 lexical representations^{32,107,108}) is sufficient to resolve the conflict or whether central control
619 (through regions such as the prefrontal cortex or PFC) is required. This distinction does not mean
620 that external control cannot possibly be involved in situations where bottom-up cues are sufficient.
621 In such cases, external control can still help facilitate faster response generation by strengthening
622 stimulus-response associations in such conditions^{91,109–111}, but this involvement is not necessary in
623 the same way as in Stroop-like tasks. The optional involvement of external control for optimizing
624 performance in such cases explains why PFC is sometimes implicated in tasks that manipulate
625 semantic similarity, and sometimes not, whereas MTG and ITG are implicated much more
626 consistently^{103,106,108,112}.

627 The discussion above showed that not all situations with high competition require external control.
628 But are tasks that do require external control, e.g., varieties of Stroop-like tasks, controlled by a
629 domain-general control mechanism? Here, I find it useful to define “domain-generality” more
630 carefully^{113,114}. Domain-generality can have multiple facets. Evidence suggests that processing
631 principles are often domain-general, as long as they are not inherently incompatible with the nature
632 of certain representations¹¹⁵. For example, the principle of performance adjustment after
633 encountering a high-conflict trial applies equally well to both linguistic and non-linguistic
634 domains^{116–118}. Neural representations can also be domain-general, in the sense that they may carry
635 out the same set of computations over representations in different domains. Association cortex and
636 certain subcortical regions have been implicated as candidates for domain-generality of control

637 90,119–124. The real question, however, is whether domain-generality in computations and neural
638 correlates translates to domain-generality in application.

639 Domain-generality in application assumes that because the same population of neurons is involved
640 in mediating control across two tasks, activating that population through increasing control
641 demands in one task will lead to the better implementation of control in the other task^{88,125}. An
642 extension of this account through merging it with neuroplasticity¹²⁶ predicts that training control
643 using one task should improve the implementation of control in other tasks^{127,128}. Empirical
644 evidence for domain-generality in application has been mixed, with some papers claiming transfer
645 of control from one task to another, mostly in language comprehension^{125,129–131}, whereas the bulk
646 of studies from the cognitive control literature point to task and domain-specific control^{93,99,132–138}.

647 In short, in terms of general principles and neural correlates, cognitive control shows evidence of
648 domain-generality across linguistic and non-linguistic domains. However, there is an active debate
649 on the domain-generality of cognitive control in application. I will discuss this controversy in light
650 of a new theory of cognitive control, the “learning account”, in the next section.

651 *The learning account of control*

652 Before I explain the learning view, I will say a few words on what motivates the learning view of
653 control. As explained earlier, while the main psycholinguistic models of language production do
654 not incorporate learning as a core feature, much evidence suggests that they should. The evidence
655 comes from the success of smaller models in explaining various behavioral effects through
656 incremental learning. For example, several studies have shown that adult speakers rapidly and
657 implicitly learn new phonotactic and orthotactic constraints embedded in strings of nonwords that
658 they recite^{11,55,139–142} (see¹⁴³ for a review). Integrating learning mechanisms into production also

659 provides an elegant explanation for facilitation and interference effects of contextual
660 similarity^{8,9,144} as explained in Box 2. In short, a growing body of evidence suggests that
661 action/production and learning are inseparable. This is the idea behind the learning account of
662 control.

663 Figures 3b and 3c contrast the traditional and learning views of cognitive control^{99,145,146}. Note that
664 both views accept the domain-generalty of neural correlates of control^{92,123} (red circles). However,
665 they make opposite predictions regarding domain-generalty in application. The traditional account
666 assumes that the key element of control is the activation of the control region. Once activated
667 through any task, this activation benefits the current task, but since it is separate from the task
668 itself, it can also benefit any other task, regardless of the overlap between the two tasks^{129,131}. In
669 contrast, the learning view posits that the key element in control implementation is the
670 strengthening of the connections between the control center and task-specific representations.
671 Since these connections are, by definition, task-specific (Fig. 3c, red connections), no benefit is
672 expected for a new task. If anything, certain learning rules, such as error-based learning could even
673 predict a disadvantage for the new task (i.e., reverse adaptation)²², as its connections to the control
674 region could get weaker according to such learning rules (see Box 2 for a parallel explanation of
675 similarity-induced interference).

676 The learning account, similar to the traditional account, predicts within-task adaptation. This
677 means that increased control demand in the current trial increases control implementation in the
678 subsequent trials of the same task¹¹⁶. But the learning account makes two unique predictions: (a)
679 since learning is, by definition, long-lasting, within-task adaptation should be resilient against the
680 passage of time and intervening trials. (b) Recruitment of control for one task should lead to null
681 or reverse cross-task adaptation in a different task. Both findings have empirical support in the

682 cognitive control literature in general^{99,147,148} and in language production, in specific^{22,149}. It is
683 worth noting that small positive cross-task adaptations^{130,131} are not incompatible with the learning
684 account, especially if mechanisms such as Hebbian learning are considered: at the end of a
685 successful trial, all active mappings are reinforced. Therefore, if both sets of stimulus-response
686 mappings across the two tasks and their connections to the control center are simultaneously
687 activated, there is a possibility to observe small positive effects. However, this effect is expected
688 to be inconsistent and weak, as it is usually not possible to keep the mappings of one task fully
689 active while performing another task, hence the ubiquity of switch costs¹⁵⁰.

690 To summarize, the learning account of cognitive control is both theoretically motivated and well-
691 supported by two critical aspects of data on adaptation, its longevity and its largely domain and
692 task-specific nature. This account maintains that, in terms of functional application, control is
693 largely domain-specific. This position is incompatible with brain training programs, which aim to
694 improve a cognitive function (e.g., language after stroke) through training working memory and
695 cognitive control in the context of different tasks and domains^{113,151}.

696 **Repair**

697 A repair refers to the replacement of one response with another, e.g., “Please pass me the salt... I
698 mean the pepper.”. Compared to other aspects of language production, repair processes have
699 received little attention, cf. ^{66,77,152}. The little empirical research that exists on the topic shows three
700 key properties: (1) At least some repairs can be extremely fast, with as little as 0 ms between
701 stopping the production of the error and initiating the repair^{153,154}. (2) Repairs are seen in children
702 as young as 2 years of age who are unable to consciously explain whether and why there was a
703 repair^{155,156}. Even in adults, repairs are not always accompanied by conscious awareness¹⁵⁷. (3)
704 Repairs do not seem to depend on accessing, or even recognizing, the correct target. For example,

705 a speaker may repair one error with another error, showing that access to the correct target is not
706 necessary for repairs. Even more interestingly, when the correct target is part of the repair, it may
707 go unrecognized as the target. For example, in an attempt to name the picture of an “orange”, an
708 individual with aphasia produced a string of responses “apple, pineapple, pumpkin, orange,
709 pineapple, peach?”, not realizing that the correct target has been produced ⁶⁶. In short, repairs can
710 be very fast, and largely independent of a conscious comparison with a correct target.

711 The mechanisms underlying linguistic repairs have remained largely obscured. Given the close
712 link between monitoring and repair, it is reasonable to expect that repairs reflect some properties
713 of monitoring. For example, it has been shown that error detection follows a bimodal distribution,
714 most likely reflecting the workings of internal vs. external monitoring mechanisms.
715 Correspondingly, repairs also show an early and a late distribution⁷⁷. Moreover, as discussed in the
716 multi-process monitoring view, certain mechanisms are better suited for detecting certain types of
717 errors, causing differences in detection and repair of semantic and phonological/phonetic
718 errors^{52,59,79}. But my goal in this section is to focus on a more fundamental issue: where do repairs
719 come from and how do they replace the error?

720 I will first propose a basic account that captures these properties. I will then augment this basic
721 account with a conflict-based monitoring-control loop¹⁵⁸, to propose an adaptive model of repairs
722 that captures more elaborate findings. The current proposal focuses on lexical repairs (replacing
723 one word with another word), but its general principles can be readily extended to cover other
724 types of linguistic repairs as well.

725 *The basic repair model*

726 An important debate about the nature of the repair process is whether, upon the detection of an
727 error, the production process is started from scratch^{159,160}, or is continued in some fashion without
728 a restart^{66,152}. The latter position is desirable for a number of reasons; it is more easily reconciled
729 with the very fast timeline of some repairs, it is cognitively less demanding, and most importantly,
730 it is compatible with the natural consequences of language production, i.e., the co-activation of
731 target and competitors. As such, a basic repair model can easily harness the basic dynamics of a
732 model of language production. Here, I propose a basic model of repair as a time-based variant¹⁶¹
733 of the Foygel and Dell's (2000) model¹⁸. In this time-based variant, activation dynamics are closer
734 to evidence accumulation models (Box 3), i.e., they start from zero and grow over time with
735 spreading activation, allowing for a more accurate representation of changes over time. Two ideas
736 are behind the basic model. The first is the notion that conflict is generally higher in error vs.
737 correct trials, discussed earlier in the Monitoring section. The second is the notion of continued
738 processing past the point of response^{61,162}. The basic repair model works by a simple *respond-&*
739 *check* mechanism. At time t , a response is made by selecting the most active representation, but
740 processing continues a little longer, up to time $t+I$, when the system makes a second selection by
741 the same rule. If the selected item matches the original selection, nothing is changed. If it does not,
742 the second selection replaces the first one (an additional utility of post-processing is determining
743 confidence in response¹⁶²).

744 Figure 4a shows this process. On correct trials (the majority of trials), conflict is consistently low
745 throughout the trial (left panel), therefore, the selected item at the times of response and check is
746 often the same (correct) response, leading to high confidence and no change. On error trials,
747 conflict is, on average, higher. If a response is selected before the system has had time to resolve
748 the conflict, the first selection may be an error (right panel). However, time often resolves conflict

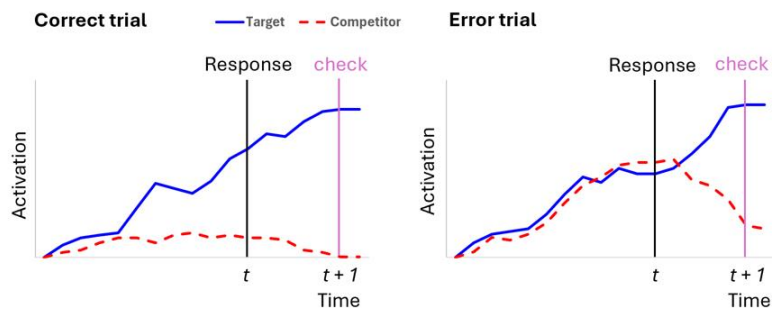
749 in favor of the correct response (see also Fig. 2b), making the second selection the correct response.
750 Repairs implemented through the respond-&-check process can be fast, because the repair has
751 been processed all along¹⁵². They are also largely subconscious, because the check mechanism is
752 the same implicit activation-based mechanism used for selection. Finally, they are independent of
753 a standard correct response. For example, if the competition is between two or more
754 representations, any one of them can get selected during the check process, regardless of its
755 correctness, allowing the model to explain false alarms of the kind observed in individuals with
756 aphasia, including the example given earlier in this section (see also ⁵²).

757 *The adaptive repair model*

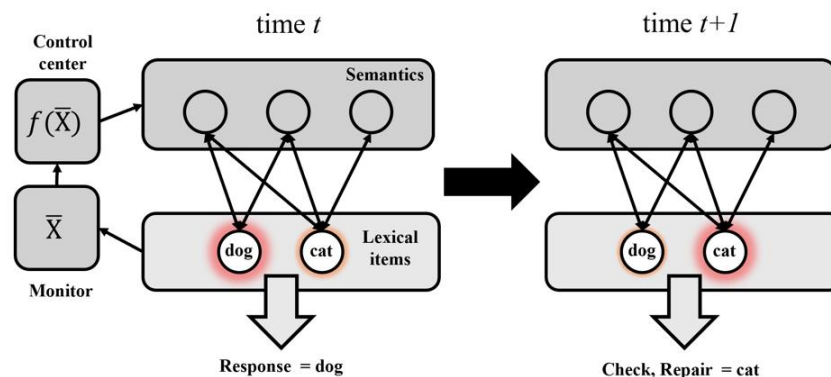
758 The basic model thus accounts for the three main properties of repairs; it is fast, it does not require
759 conscious processing or a correct target. However, it has no mechanism to adapt to difficult
760 situations. Current findings suggest that when the probability of an error increases, so does the
761 probability of a repair^{50,66}. This finding has the same flavor as within-task adaptation, discussed in
762 the Control section. I will thus tackle this problem by situating the basic repair model in a
763 monitoring-control loop triggered by conflict (see also Gauvin & Hartsuiker, 2020, for a similar
764 proposal)^{158,161}. Figure 4b shows this adaptive model. The input activates the semantic features,
765 and subsequently, lexical representations, where the respond-&-check mechanism is implemented.
766 Conflict is continuously monitored at this level, providing the system with an average of conflict
767 over all trials, weighted more heavily towards the most recent trial(s). If the average conflict
768 around the time of the first selection (response) surpasses a certain threshold, control is recruited
769 to boost the correct semantic-lexical mapping for the second selection (check). The higher the
770 conflict level, the larger the boost. This results in a higher proportion of repairs in more error-prone
771 situations, compatible with the empirical findings¹⁶¹.

772 To recap, the adaptive repair model harnesses the basic dynamics of psycholinguistic models,
 773 combines it with conflict-based monitoring and control, and uses insights from the decision-
 774 making literature on threshold setting and post-response processing. This allows the model to
 775 explain the three basic properties of repairs mentioned earlier. Moreover, the model implements
 776 the notion of learning by computing a weighted average of conflict over many trials to be used as
 777 the regulating signal. This allows the model to explain the increase in repair rates in the face or
 778 higher error rates. Moreover, the learning mechanism can accommodate both sustained control, as
 779 well as trial by trial, fluctuation in control needs¹⁶³. I must note that this proposal is quite new, and
 780 thus open for testing. Future studies and empirical data will determine how well this model will
 781 fare and what needs to be changed. Also, I hope that this proposal inspires alternative proposals
 782 that may fare even better than the current model.

783 **(a) The respond-&-check mechanism in the basic repair model**



788 **(b) The adaptive repair model**



793 *Figure 4. The repair model changing the error “dog” to the correct response “cat”. (a) The*
794 *respond-&-check mechanism in the basic model for a correct trial (left) and an error trial (right).*
795 *Reselection of the response in the former leads to high confidence and no additional action. In the*
796 *latter, the changed outcome of selection triggers the replacement of the prior response with a*
797 *repair. (b) The adaptive repair model. The basic repair process of respond-&-check is situated*
798 *within a monitoring and control loop triggered by a weighted average of conflict. Red indicates*
799 *greater activation than orange.*

800

801 **Is there an “ideal” model?**

802 Throughout the paper, I have discussed the differences between psycholinguistic and motor speech
803 models, and how these differences bear on how language production is monitored and regulated.
804 In this final section, I will tackle the question of "an ideal" model. Is an ideal model a "mega-
805 model" that combines the models from the two traditions? As George Box famously said, “All
806 models are wrong, but some are useful.”. Therefore, the question of an ideal model may be better
807 phrased as the question of a useful model. Many of the existing models are useful for understanding
808 a target phenomenon. For example, if the purpose is to test whether non-competitive selection is
809 compatible with behavioral interference, a simple model with basic representations and an error-
810 based learning mechanism does the job⁹. However, if the purpose is to explain both taxonomically-
811 induced interference and thematically-induced facilitation within the same system, then the model
812 needs to have a more sophisticated representation of the semantic space⁸. More complex models
813 explain more data but are also harder to implement and understand. Therefore, a "mega-model" is
814 only motivated if one really needs to model the whole production chain from beginning to end.

815 On the one hand, behavioral and neural data, as well as computational implementations, have
816 pointed to a globally modular, locally interactive system^{60,164}. This means that cascading and
817 feedback affect the adjacent layers much more than distant layers. If so, we may not need a mega-
818 model. For example, perhaps going up to the lexical level could be perfectly sufficient for
819 modeling articulatory processes. On the other hand, some aspects of production will be left out by
820 this approach. For instance, focused elements in linguistic messages tend to be acoustically
821 prominent¹⁶⁵. This finding links semantic representations to articulatory ones at the two ends of
822 the production system. A model with a narrower scope will simply miss some of the relevant
823 representations or must speculate on how processing takes place among those representations.
824 More generally, if we are to understand the regulation of the language production system through
825 hierarchical model-based RL theory (Box 4), we must train models that map the entire process.
826 This approach is critical for assessing whether such a framework applies to a highly generative
827 system like language production. Moreover, it allows us to better understand the kinds of
828 information used in earlier stages to assess a final outcome¹⁶⁶.

829 In short, I believe some principles like cascading of activation, interactivity, co-activation of
830 similar representations, speaker's goals especially in terms of emphasis on speed vs. accuracy, and
831 implicit learning must always be considered when modeling a certain linguistic phenomenon. On
832 the other hand, the scope of model's representations depends on the purpose of modeling. For
833 certain claims to be verifiable, a mega-model is indeed necessary.

834 **Conclusion**

835 My goal in this paper was to combine insights from different traditions of language production
836 research, as well as advances in other fields of cognition, to propose new directions for research
837 on word production. I will summarize the conclusions in four points, together with their potential

838 contribution to future directions. The first two points are focused on specific mechanisms. The last
839 two points are broader takeaways.

840 **1. A multi-process monitoring view.** Motor speech and psycholinguistic traditions differ in some
841 of the mechanisms they propose for monitoring and control of language production. These
842 differences do not necessarily hint at a problem with one approach or the other. Rather, they likely
843 reflect important differences in the nature of representations that are the focus of each tradition.
844 Therefore, instead of choosing the “right” monitoring mechanism, a more fruitful approach could
845 be to view monitoring as a multi-mechanism process. Embracing the multi-process monitoring
846 view shifts the focus of future research to important open questions, such as the relative
847 contribution of various mechanisms to monitoring different aspects of language production, the
848 kind of information used for monitoring at different stages of processing, and better ways of
849 leveraging the complementary role of these mechanisms for rehabilitation after brain damage.

850 **2. A repair mechanism embedded in the monitoring-control loop.** The adaptive repair model,
851 proposed here, takes the idea of continued processing past the selection point and embeds it within
852 the same conflict-driven monitoring-control loop that controls the primary production process.
853 This account is parsimonious, because control is always applied the same way, but depending on
854 how quickly it takes effect it may either prevent an error or facilitate a repair. This model, however,
855 is in its nascency. Many issues remain open to investigation such as the timeline of conflict
856 monitoring during a trial, as well as the correct functions for weighting the recency of conflict and
857 scaling of control.

858 **3. Learning and production as one.** For reasons stated in this paper, I believe that learning plays
859 a critical role in correctly understanding a range of behavioral findings from rapid adjustment to
860 new constraints to facilitatory and inhibitory effects of contextual similarity, to control and repair

861 processes. Fortunately, psycholinguistic models lend themselves well to the integration of learning
862 mechanisms such as error-based and Hebbian learning. Future work should consider the power of
863 learning accounts in explaining new phenomena, even when such phenomena seem to have little
864 to do with learning in its pedagogical sense.

865 The implementation of learning mechanisms should not be restricted to the inner workings of the
866 language production system, but should also extend to its interactions with other systems. A
867 broader picture is emerging in the cognitive control literature pointing to the tight link between
868 action and learning. An example is the learning view of cognitive control^{94,145,146}. This view
869 predicts that domain-generality in the neural underpinnings of control actually leads to domain-
870 specificity in the application of control, and is supported by evidence from both language
871 production and non-linguistic tasks. Embracing this view and its application to language
872 production is an excellent step towards answering more nuanced questions, such as how the
873 parameters of such learning are set in different populations and under different circumstances.

874 ***4. Language production studied within a decision-making framework.*** Much of the discussion
875 in the current paper draws on principles and mechanisms from fields of cognition other than
876 language. I have shown how applying SDT to distributions of conflict for correct and error
877 responses can introduce useful concepts such as criterion setting into debates of selection and
878 monitoring. This framework can also be applied to information used by other accounts. Other
879 decision making models have also been used and have advantages over SDT^{167,168}. But there are
880 also challenges in applying such models to the complex, non-linear process of word production¹⁶⁹
881 (Box 3). Resolving these challenges is only possible with a closer collaboration between language
882 and decision scientists, but it is an effort with a high payoff for both fields.

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887 **Competing interests**

888 The author declares no competing interests.

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